RESEARCH PAPER

Coupled thermo-hydro-mechanical model for porous materials under frost action: theory and implementation

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Received: 3 February 2011/Accepted: 2 May 2011/Published online: 15 May 2011 © Springer-Verlag 2011

Abstract This paper introduces the development and implementation of a multiphysical model to simulate the coupled hydro-thermo-mechanical processes in freezing unsaturated porous materials. The model couples the Fourier's law for heat transfer, the generalized Richards' equation for fluid transfer in unsaturated media, and the mechanical constitutive relationship. Coupling parameters were defined to transfer information between field variables. Relationships, such as the similarity between drying and freezing processes and the Clapeyron equation for thermodynamic equilibrium during phase transition, were utilized to describe the effects of frost action. The coupled nonlinear partial differential equation system was solved under typical boundary conditions. The simulation results indicate that the model properly captured the coupling characteristics such as the thermally induced hydraulic and mechanical change in porous materials. Simulation was also conducted on an instrumented pavement section. The results of multiphysical simulations match reasonably well with the field-monitoring data.

Keywords Frost action · Hydro-thermo-mechanical model · Multiphysical model · Pavement · Unsaturated porous media

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1 Introduction

Multiphysical processes are responsible for many interesting phenomena in unsaturated porous materials, e.g., hydro-diffusion and subsidence, drying and shrinkage, freezing and spalling, and capillarity and cracking [13]. There are generally two or more physical fields involved in these multiphysical processes. In some cases, the effects of coupling are not only noticeable but also critical. For example, the thermo-hydro-mechanical process can lead to noticeable stresses or deformations even without external loads. In many cases, multiphysics modeling is not only theoretically superior to solving individual unrelated processes but also practically necessary. The development of a sound multiphysics model requires understanding the fundamental mechanisms and the proper application of modeling techniques to obtain reliable simulation results.

The fundamental behaviors of porous materials under frost action have been investigated by means of experimental, analytical, or numerical approaches. Some research has focused on specific properties of porous materials, e.g., the hydraulic conductivity [18, 20, 32, 38, 56, 63], or the relationships between different parameters, e.g., the soil– water characteristic curve (SWCC, [19, 30, 37, 47, 52, 63]). Some other studies investigated the frost effects and the coupling mechanism [6, 7, 15, 21, 26, 46]. The forms of the governing equations for individual fields have also been investigated (i.e., [9, 10]).

The description of freezing porous materials inevitably involves more than one physical field, e.g., TH (thermohydraulic fields) or THM (thermo-hydro-mechanical fields) model. The development of modeling techniques for THM method has benefited from the advances in multiphysics research and simulation tools. For example, there are a substantial number of papers about the coupled thermo-

Paper presented at the International Workshop on Multiscale & Multiphysics Processes in Geomechanics, June 23–25, 2010, Stanford University.

hydro-mechanical (THM) model or thermo-hydromechanical-chemical model (THMC) for rocks and soils [2, 44, 49, 50, 58–62]. Noteworthily, these models were developed either from the non-isothermal consolidation of deformable porous media or from an extension to Biot's phenomenological model and generally did not consider the phase change of water (i.e., freezing/thawing phenomena) in porous media. They, however, can be extended to account for the effects of phase changes of water. The coupling models were usually solved by numerical method (finite difference (FD), finite element method (FEM), or finite volume (FV)) due to the highly nonlinear governing equations and complicated boundary conditions.

In conjunction with theoretical modeling efforts, tremendous amounts of work have been conducted to address practical issues in civil engineering, soil science, and agricultural engineering related to freezing porous materials, such as deterioration of geomaterials in frost regions. Questions raised from practice include the prediction of frost heave, the moisture and temperature redistribution, etc. Studies for addressing these issues usually led to TH or THM models, which can be categorized as rigid-ice models [35, 45, 54], thermodynamic models [22–24, 27, 28, 40, 42, 43], semi-empirical models [29, 41], and poromechanical models [13, 14].

The effects of freezing/thawing have been recognized as major factors causing the deteriorations of pavement structures in cold regions [55]. Both temperature and moisture content variations can pose significant environmental loads on pavement structure. Accurate prediction of pavement temperature from air temperatures will help pavement engineers to perform back-calculations of pavement moduli [67]. Moreover, the modulus of each pavement layer is also greatly affected by the moisture content, which significantly influences the pavement performance [68]. Moisture-induced damage of asphalt mixtures, referred as stripping, is one of the most detrimental factors affecting the in-service performance of asphalt pavements [11]. The ability to predict the temperature and moisture content distributions in a pavement will help to assess the performance of the pavement. For such purpose, several models have been proposed such as the Enhanced Integrative Climate Model (EICM) from The Federal Highway Administration. The limitations of EICM include (1) one-dimensionality and (2) neglecting the coupling effects of different fields. A few other coupled models have also been developed for this purpose [3, 53, 67]. The mechanical field, however, was not coupled in these models. Properly simulating the coupling effects on the mechanical and structural behaviors of pavement is essential for further advancing pavement research and practices.

This research aims to develop a coupled multiphysics simulation model to investigate the behaviors of porous materials under frost action. A theoretical framework is established to formulate the coupled thermo-hydromechanical processes in freezing porous materials. The coupled model was solved numerically by finite element method. The performance of this model is validated by comparing simulation results with field data collected in an instrumented pavement. The simulation results predict typical phenomena observed in freezing unsaturated porous media, such as thermal-induced moisture migration, ice front development, and freezing-caused scaling of geomaterials. Furthermore, the model was applied to analyze an instrumented pavement. The simulation results closely match the field-monitoring data.

2 Theoretical basis

2.1 Thermal field

The thermal field is usually the main cause of multiphysical processes in freezing soils. For example, during the frost heave process, the sub-freezing temperatures cause the advancement of the frost front, which in return induces the fluid migration and soil deformation. This process produced by energy dissipation within the multiphase media can be alternatively explained as results of the varied surface tension, soil moisture suction, and kinetic energy changes associated with the hydrogen bond distribution, as well as thermally induced osmotic gradients [6, 7]. Besides the temperature-induced moisture flux or deformation, the energy carried by migratory fluid and the heat parameters influenced by fluid transport and metamorphic solid skeleton are also assumed as the 'reactions' to the temperature field. To precisely formulate energy transport in porous materials, a modified Fourier's equation with both conduction and convection terms (Eq. 1) was adopted.

$$C_a \frac{\partial T}{\partial t} = \nabla \cdot (\lambda \nabla T) - C_w \nabla (\mathbf{J}T)$$
(1)

where C_w is the heat capacity of unfrozen water, C_a is the apparent heat capacity, λ is the thermal conductivity, T is the temperature, t is time, and **J** is the water flux from the hydraulic field. Both C_a and λ are coupling variables. The moisture migration changes the soil composition and consequently C_a and λ , which in turn affects the heat transfer process.

The effects of the air phase and radiation were neglected as the phase transition of water predominates in the process of energy conversion. The apparent volumetric heat capacity C_a in Eq. 1 takes into account the energy released/ absorbed by the phase change of water. Instead of being treated as an energy sink or source on the right-hand side of the Fourier's equation, the enthalpy change due to the phase change can be incorporated into the heat capacity to reduce the nonlinearity [1].

$$C_a = C_s \theta_s + C_w \theta_w + C_i \theta_i + C_v (n - \theta_w - \theta_i) + L_f \frac{\mathrm{d}\theta_i}{\mathrm{d}t} \qquad (2)$$

where θ_s , θ_w , and θ_i denote the volumetric content of soil mass, unfrozen water, and ice particles, respectively (the volume change of soil skeleton is neglected here). The same convention on subscripts applies to the other parameters. L_f is the latent heat.

The thermal conductivity λ in Eq. 1 can be approximated by empirical relationships such as in Eq. 3 [8, 23, 34]. There are also other similar relationships such as the equations proposed by Gardner [20], Sawada [51], and Campbell [5].

$$\lambda = C_1 + C_2(\theta_w + \theta_i F) - (C_1 - C_4)$$

$$\cdot \exp\left\{-\left[C_3(\theta_w + \theta_i) + F\theta_i\right]^{C_5}\right\}$$
(3)

$$F = 1 + F_1 \theta_i^{F_2} \tag{4}$$

where C_1 , C_2 , C_3 , C_4 , C_5 , F_1 , and F_2 are empirical curvefitting constants.

2.2 Hydraulic field

For variably unsaturated porous media, the fluid movement is generally described by the mixed-type Richards' equation, which was shown to have good performance in ensuring mass conservation [9]. To extend the Richards' equation, a term related to ice formation needs to be added to the left-hand side of the Richards' equation to obtain Eq. 5.

$$\frac{\partial \theta_w}{\partial t} + \frac{\rho_i}{\rho_w} \frac{\partial \theta_i}{\partial t} = \nabla \cdot (K_{\rm Lh} \nabla h + K_{\rm Lh} i + K_{\rm LT} \nabla T)$$
(5)

where θ_w is the volumetric content of water, θ_i is the volumetric content of ice, ρ_w is the density of water, ρ_i is the density of ice, K_{Lh} is the hydraulic conductivity, K_{LT} is the hydraulic conductivity due to thermal gradient, **i** is the unit vector along the direction of gravity, and *h* is the matric potential head (or pressure head). The matric potential head is the equivalent water head (unit: m) of the matric potential (unit: Pa). The two quantities are mathematically related via the unit weight of water. The concept of matric potential is used throughout this paper except for equations, where concept of the matric potential head is used.

Based on the analogy of freezing and drying processes, it has been accepted that the concept of the soil-water characteristic curve (SWCC) can be extended to describe the relationship between unfrozen water content and the matric potential (negative water suction) [30, 57]. The hydraulic conductivity can be estimated by integration of the SWCC [12, 18, 38]. This study employed either the simplified van Genuchten's equation ([23, 63], Eq. 6) or Fredlund's equation [19] when necessary data are available to describe the SWCC. Different approaches were then adopted to predict the hydraulic conductivity based on the SWCC.

$$S_e = \frac{\theta - \theta_r}{\theta_s - \theta_r} = \left(1 + |\alpha h|^n\right)^{-m} \tag{6}$$

where S_e is the effective saturation, θ_s and θ_r are the saturated and residual water content, respectively, and α , *m*, and *n* are empirical parameters.

 $K_{\rm Lh}$ and $K_{\rm LT}$ are hydraulic conductivities related to pore water head and temperature, respectively. One set of accepted relationships for these parameters are:

$$K_{\rm Lh} = K_s S_e \left[1 - \left(1 - S_e^{1/m} \right)^m \right]^2$$
(7)

$$K_{\rm LT} = K_{\rm Lh} \left(h G_{wT} \frac{1}{\gamma_0} \frac{\mathrm{d}\gamma}{\mathrm{d}T} \right) \tag{8}$$

where γ denotes the surface tension of soil water, which is temperature dependent and can be approximated as $\gamma = 75.6 - 0.1425T - 2.38 \times 10^{-4}T^2$; γ_0 is the value of γ at 25°C, i.e., $\gamma_0 = 71.89 \times 10^{-3}$ kg m³.

As shown in Eq. 7, the hydraulic conductivity in partially saturated or partially frozen soil, K_{Lh} is obtained by multiplying the saturated conductivity with a saturationdependent 'relative conductivity' term. The thermalinduced hydraulic conductivity in Eq. 8 was developed from the thermodynamics theory [46]. G_{wT} is a gain factor, which has a value of around 7 for coarse-grained soils [45]. The dependence of viscosity on temperature was neglected here to unify the equations for the intrinsic hydraulic conductivity and the hydraulic conductivity.

The role of ice as an impedance for fluid migration was first proposed by Harlan [24] while studying the unsaturated hydraulic conductivity in partially frozen media. This viewpoint was confirmed by subsequent researchers such as Jame (1978) and Hansson et al. [23]. An impedance factor was adopted to describe the effects of ice on the fluid migration. However, a few pieces of recent research proposed that the impedance factor is unnecessary as long as the SWCC is precisely determined [39, 64].

When phase changes are involved, the generalized Clapeyron equation (Eq. 9) was used to describe the condition for the co-existence of water and ice. The local freezing point of pore fluid can be obtained from the generalized Clapeyron equation (Eq. 9).

$$\frac{\mathrm{d}h}{\mathrm{d}T} = \frac{L_f}{gT} \tag{9}$$

where *h* is the water head, L_f is the latent heat of water, and *g* is gravitational acceleration.

Assuming thermodynamic equilibrium conditions are maintained at the ice-pore/water interface at infinitesimal time intervals, the Clapeyron equation can be used to determine the ice content via Eq. 10.

$$\frac{\mathrm{d}\theta_i}{\mathrm{d}T} = \frac{L_f}{gT} \frac{\mathrm{d}\theta}{\mathrm{d}T} \tag{10}$$

3 The stress and strain field

The governing equation for the stress field is the Navier's equation, which incorporates the equation of motion, strain–displacement correlation, and the constitutive relationship. The equation of motion (Equation of equilibrium) is introduced in general tensor format as,

$$\nabla \cdot (\mathbf{C}\nabla \mathbf{u}) + \mathbf{F} = \rho \ddot{\mathbf{u}} (\nabla \cdot (\mathbf{C}\nabla \mathbf{u}) + \mathbf{F} = 0)$$
(11)

where \mathbf{u} is the displacement vector, \mathbf{C} is the fourth-order tensor of material stiffness, and \mathbf{F} is the body force vector.

The strain-displacement equation is,

$$\boldsymbol{\varepsilon} = \frac{1}{2} \left[\nabla \mathbf{u} + \left(\nabla \mathbf{u} \right)^T \right] \tag{12}$$

The constitutive equation is

$$\boldsymbol{\sigma} = \mathbf{C} : \boldsymbol{\varepsilon} \tag{13}$$

where, σ is the Cauchy stress tensor, ε is the infinitesimal strain tensor, and the symbol ":" stands for double contraction.

In order to consider the influence of the thermal field and the hydraulic field on the stress field, the constitutive relationship for porous materials has to be formulated as

$$\boldsymbol{\sigma} = \mathbf{D}\boldsymbol{\varepsilon}_{el} + \boldsymbol{\sigma}_0 \tag{14}$$

where **D** is the stiffness matrix of soil skeleton, σ_0 is the initial stress vector, and ε_{el} is the elastic strain that can be obtained from the following relationship

$$\boldsymbol{\varepsilon} = \boldsymbol{\varepsilon}_{el} + \boldsymbol{\varepsilon}_{th} + \boldsymbol{\varepsilon}_{tr} + \boldsymbol{\varepsilon}_{hp} + \boldsymbol{\varepsilon}_0 \tag{15}$$

where ε_{th} is the strain caused by thermal expansion, $[\alpha(T - T_{ref}), \alpha(T - T_{ref}), 0]^T$; ε_{tr} is the strain caused by the phase change of water, which was approximated as $[0.09Q, 0.09Q, 0]^T$ when a unit localization tensor in mixture theory is followed, where Q is the degree of water phase transition, and 0.09 is the relative change of volume when water turns into ice; ε_0 is the initial strain; and ε_{hp} is the strain resulting from the change of the matric potential, which is calculated by $[h/\mathbf{H}, h/\mathbf{H}, 0]^T$. **H** is a parameter similar to the modulus corresponding to matric potential. The value of **H** can be obtained though experimental measurement. The use of H casts light on the independent role of matric potential in the constitutive relationship of unsaturated porous media as indicated in Biot's model for unsaturated fluid with air bubble and in Fredlund's method to address volume change of unsaturated soil [4, 17].

3.1 General boundary condition

The general boundary condition, which includes the special cases such as the Dirichlet (first type), Neumann (second type), and Robin (third type) boundary conditions, was formulated by Eq. 16

$$\mathbf{n} \cdot (c\nabla u + \varsigma u - \gamma) + qu = \delta - \mathbf{h}^T \mathbf{\mu}$$
(16)

where **n** is the outward normal unit vector of a boundary, *u* is the dependent variable of individual field (temperature, matric potential, displacements, etc.), *c* is a conductivity term, ς is the conservative flux convection coefficient, γ is the source in the subdomain, *q* is the boundary absorption coefficient, δ is the boundary source, **h**^T is a matrix designated for the flexibility of the constraint type, and **µ** is the matrix of Lagrange multiplier.

4 Model implementation

The couplings of the three physical fields (i.e., hydraulic, thermal, and mechanical fields) were realized by means of variables and parameters that transfer information interactively. Due to the high nonlinearity, the equations have to be solved numerically. The coupled multiphysical model was solved with the assistance of COMSOL, a commercial multiphysics simulation platform. Firstly, the model geometries were constructed by the interactive graphic interface. The models were then customarily built, transformed into the weak form, and solved using the nonlinear solver provided by COMSOL. The results were analyzed using the postprocessing functions provided by the software.

5 Simulation case I

Mizoguchi [36] conducted a classic benchmark experiment where four identical cylinder samples of 10 cm length and 8 cm height were packed with sandy loam. The initial temperature was 6.7° C, and volumetric water content was 0.33. The samples were thermally insulated in the sides and in the bottom. The top surface was exposed to a constant temperature of -7° C. After 12, 24, and 50 h, respectively, the samples were taken out and divided into 1-cm-thick slices to measure their water content distribution. The process was simulated by Hansson et al. [23] with a thermo-hydraulic algorithm. This experiment was chosen as the prototype for computational model construction in simulation case I.

A computational domain of 10 cm in length and 8 cm in height was used in the simulation. The initial temperature was 6.7°C, and volumetric water content was 0.33. The samples were thermally insulated (Neumann boundary condition, zero thermal gradient) in the sides and in the

bottom. The top surface was exposed to a constant temperature of -7° C. The thermal boundary conditions are shown in Fig. 1. The heat influx in the surface was described by Newton's law of cooling as Eq. 17

$$\mathbf{n} \cdot (\lambda \nabla T) = h_c (T_{\text{amb}} - T) \tag{17}$$

where λ is the thermal conductivity, h_c is the coefficient of convection heat transfer, T_{amb} is the ambient temperature, and *T* is the temperature at boundaries. All boundaries were hydraulic insulated (Neumann boundary condition, zero hydraulic gradient or no flow) to ensure mass conservation, which is mathematically described as

$$\mathbf{n} \cdot (K_{\mathrm{Lh}} \nabla h + K_{\mathrm{Lh}} \mathbf{i} + K_{\mathrm{Lh}} \nabla T) = 0 \tag{18}$$

To implement the multiphysical simulation, the differential equations were first transformed into weak forms. Taking the Fourier's equation for example, the weak form is

$$\int_{\Omega} \left(\frac{\partial \theta}{\partial t} + \frac{\rho_i}{\rho_w} \frac{\partial \theta_i}{\partial t} \right) v dV$$

=
$$\int_{\partial \Omega} \mathbf{n} \cdot \left((K_{\rm Lh} \nabla h + K_{\rm Lh} \mathbf{i} + K_{\rm Lh} \nabla T) v \right) dS$$

+
$$\int_{\partial \Omega} (K_{\rm Lh} \nabla h + K_{\rm Lh} \mathbf{i} + K_{\rm Lh} \nabla T) \cdot \nabla v dV$$
(19)



Fig. 1 FEM mesh for the computational domain with thermal boundary conditions

where v is a nonnegative weighting function whose integration over domain Ω equals 1.

Some soil parameters for the hydraulic field can be found in Hansson's study [23]. Other parameters were set based on experimental data and related literature [17, 48]. The data are listed in Table 1.

The influence of ice content on the elastic moduli of soils is complicated. In this simulation, a simplified linear relationship was assumed between the ice content and the modulus of elasticity. This assumption was based on the experimental results on the effects of degree of freezing on the modulus of soils.

6 Results and analysis

The typical thermal properties, i.e., apparent heat capacity and thermal conductivity, are heavily dependent on the hydraulic field and the phase change of water. This dependence usually results in high nonlinearity that can significantly affect the multiphysical process. Plotted in Fig. 2 are the variations of the volumetric heat capacity and thermal conductivity with time at heights of 5, 10, 15, and 18 cm. It can be seen that the apparent heat capacity in Fig. 2a slightly decreases with time before temperature drops below the freezing point. This agrees with the fact that the water content decreased before ice starts to form. After icing starts, the progress of water turning into ice releases a considerable amount of heat that decelerates substantially the freezing process. This is equivalent to an increase in the apparent heat capacity. Therefore, the sudden increase in apparent heat capacity indicates the increasing contribution of latent heat of ice formation. The variation of the thermal conductivity follows a similar pattern, but demonstrating a less extent of nonlinearity.

The temperature distributions at different times are sketched in Fig. 3. Temperatures at all points drop as energy is extracted from the upper boundary. The overall rate of temperature change decreases as temperatures at some locales approach the freezing point. But it is worthwhile to point out that the freezing point of pore water is slightly lower than 0°C, a phenomena called freezing point depression. The depression of the freezing point of pore water refers to the difference between the local freezing point and the freezing point under standard atmospheric pressure (0°C). The extent of freezing point depression is determined by the pore size. Small pore produces large suction and consequently causes a larger amount of freezing point depression. The depressions of the freezing points in different locales are shown in Fig. 4. It is seen that the freezing point is not uniform throughout the computational region. But in fact, it turns out to be lower in

Table 1 Constant parameters for simulation case I

Constant	Value	Units	Description
h _c	28	W/m ² K	Convection heat transfer coefficient
C_1	0.55	W/m ² K	Constant for thermal conductivity 1
C_2	0.8	W/m ² K	Constant for thermal conductivity 2
<i>C</i> ₃	3.07	W/m ² K	Constant for thermal conductivity 3
C_4	0.13	W/m ² K	Constant for thermal conductivity 4
<i>C</i> ₅	4	1	Constant for thermal conductivity 5
F_1	13.05	1	Constant for thermal conductivity 6
F_2	1.06	1	Constant for thermal conductivity 7
C_n	2×10^{-6}	J/m ³ K	Volumetric heat capacity of solid
C_w	4.2×10^{-6}	J/m ³ K	Volumetric heat capacity of liquid
C_{v}	1.2×10^{-3}	J/m ³ K	Volumetric heat capacity of vapor
C_i	1.935×10^{-6}	J/m ³ K	Volumetric heat capacity of ice
L_{f}	3.34×10^{-5}	J/kg	Latent heat of freezing or thawing of water
θ_0	0.33	m^3/m^3	Initial water content
θ_r	0.05	m^3/m^3	Residual water content
θ_s	0.535	m^3/m^3	Saturated water content
K_s	3.2×10^{-6}	m/s	Saturated hydraulic conductivity
α	1.11	l/m	Empirical parameters 1 for hydraulic properties
n	1.48	1	Empirical parameters 2 for hydraulic properties
т	0.2	1	Empirical parameters 3 for hydraulic properties
l	0.5	1	Empirical parameters 4 for hydraulic properties
γo	71.89	g/s ²	Surface tension of soil water at 25°C
ρ_i	931	kg/m ³	Density of ice
$ ho_w$	1,000	kg/m ³	Density of water
ρ_n	2,700	kg/m ³	Density of soil solids
T_0	6.7	°C	Initial temperature
T _{amb}	-6	°C	Ambient temperature
g	9.8	m/s ²	Gravitational acceleration
μ	0.3	1	Poisson ratio
Н	7,653	m	Modulus related to matric potential
al	0.8×10^{-6}	1/K	Thermal expansion coefficient

layers adjacent to the upper boundary. Moreover, the freezing point continuously decreases versus time as freezing develops. The simulation results confirmed that there exists an obvious freezing point depression of water in porous media. The magnitude of the depression is dependent on the pore characteristics such as the pore size and the associated capillary action.

Accurate prediction of frost penetration, i.e., the depth of frost front, is essential for studying the frost action in porous media and is thus of great practical interest. In this study case, frost penetration can be plotted based on temperature variations in Fig. 3 and freezing point depression in Fig. 4. In comparison with the results predicted by an empirical equation [48], we found that the magnitude of the frost penetration predicted by the current model is greater than that calculated by the empirical equation (in Fig. 5). One possible reason for the difference is that the empirical equation overlooks the influence of the hydraulic field and consequently the dramatic change on the thermal properties of soil. Therefore, the calculation with constant soil properties in the commonly used empirical equation may lead to a noticeable underestimation of the frost penetration depth.

Figure 6 plots the distribution of the total volumetric water content (the volumetric water content plus the volumetric ice content) at different times. The curves clearly demonstrate a trend that moisture migration moves toward the freezing front [29, 30]. This is consistent with commonly observed frost heave phenomena. Such phenomena have significant impacts on the pavement, foundations, and infrastructures. The total volumetric water content (including both in the liquid and solid state) is determined by both the temperature and matric potential. The unfrozen water content is determined by the water retention curve,



Fig. 2 The variations of the thermal properties versus time

while the amount of ice is decided by the ice–water balance together with the mass balance. Temperature gradient is the driving factor for all the migration phenomena in this case. This is because the temperature gradient causes the hydraulic gradient, which then drives the moisture migration. When the matric potential satisfies the required temperature and pressure conditions for ice formation (described by the Clapeyron equation), water begins to turn into ice. In this model simulation, it was assumed that the water-ice balance is maintained in each infinitesimal time step. As shown in Fig. 6, the water content in the cold region (upper) of the model increases. At the same time, moisture from lower region migrates upward and gradually turns into ice.

The variation of ice distribution can also be predicted. As shown in Fig. 7, ice formed above the depth of frost penetration. The comparison of the ice content at 12, 24, and 50 h after freezing starts indicates that water continuously migrates into frozen area and turns into ice therein. The process is determined by both the thermodynamic equilibrium between ice and water and the water flow in the unsaturated porous media. The figure shows that at the beginning of freezing, the velocity of ice formation is very fast. The surface layer accumulates the greatest amount of ice.

Matric potential is essential to the mechanical properties of unsaturated porous materials, i.e., the shear strength of unsaturated soils (Vanapalli 1996). In this simulation, matric potential is a dependent variable of the hydraulic field that can be explicitly calculated. As shown in Fig. 8, the spatial distributions of matric potential head at different freezing times. The matic suction head, which is the negative of the matric potential head, is illustrated in Fig. 8. Its



magnitude is directly related to the liquid water content. It is shown that suction increases as liquid water content decreases, although the total ice and liquid water content may increase.

Figure 9 shows the variation of vertical deformation (or frost action) versus time. Given that the bottom of the sample was fixed, the vertical deformation can be determined from the average displacement on the top of the specimen. The volume changes as a result of the temperature change, the variation of matric potential, and the ice formation. The trend of volume change occurs in stages. In the 1st stage, the volume change is dominated by the thermal contraction of solids. However, the magnitude is negligible due to the small soil thermal expansion coefficient and the small range of temperature variation. The volume change is affected by two major phenomena in the 2nd stage, i.e., the volume contraction due to increase in matric potential and the volume expansion due to phase change (ice has around 10% larger specific volume than water). The increasing matric potential (as seen in Fig. 8) holds the particles tighter, leading to the amount of volume reduction counteracting the increases in the volume due to phase change of water. The trend of volume change from computational simulation implies that the effect of matric potential on volume change dominates over that by the phase change. This even caused volume contraction during certain period in the 2nd stage. In the 3rd stage, the volume continues to increase due to the volume increase associated with phase transition. The simulation is consistent with the experimental phenomena observed by Liu et al. [31].

Figure 10 shows the distribution of the vertical stress in the specimen due to freezing. The positive sign indicates tension. Both the maximum tensile and compressive



Fig. 3 Temperature profile at different freezing times

stresses appear in the surface layer. The reason is that the moisture migrates and accumulates near the surface. The volume expansion due to ice crystallization leads to the internal stresses. It has been commonly observed that during thermal weathering of rocks in mountain areas, cracks typically appear first on the surface and then progresses to the interior. The stress distribution illustrated in Fig. 10 gives an explicit explanation on the fracture mechanism, since the high-tension and compression zones close to the surface are likely to initialize the formation of cracks. Besides, the simulation provides some insight into factors that control the crack spacing. However, the relationship between the thermal gradient, moisture gradient, internal stress, and crack spacing requires further investigations.

7 Simulation case: II

An instrumented road in Ohio, USA, was used as test bed to further validate the simulation model. The Ohio Department of Transportation launched a project in 1995 as a part of Strategic Highway Research Program (SHRP) Test Road [25, 33, 65]. A series of 34 instrumented pavement test sections were constructed on State Road 23 in Delaware County, Ohio, USA. The field sensors monitored the moisture content, resistivity, and frost depth as well as the air temperature. Additional information such as water table height is also available for sections that were originally designated for the assessment of seasonal effects on both Portland cement concrete pavement (rigid) and asphalt concrete pavement (flexible). Here, we selected



Fig. 4 Variation of freezing point depression along the depth at 0, 12. 24 and 50 h



Fig. 5 The depths of frost penetration versus time

Section 390204 for the simulation study. The section consists of 11 inches of asphalt concrete pavement and 6 inches of aggregate base. Eighteen temperature gauges and 10 moisture gauges were installed within the pavement structure. Hourly air temperature and local soil temperature at each gauge were accessible. Moisture content information was available on the 1st, 9th, and 20th day. The period of simulation is between December 3 and December 22 in 1999.

7.1 Modeling

The computational domain, which is half of the pavement and embankment, is shown in Fig. 11. The geometry of the FEM model was constructed based on the real dimensions of the pavement structure and embankment. Tentative calculation was conducted to make sure the computational domain is big enough to eliminate truncation effects on the simulation boundaries. Rectangular elements were employed in the FEM meshing.

Equations proposed by [18] was used to obtain the SWCCs of base and subgrade materials, i.e.,

$$\theta_{w} = C(h) \times \left\{ \frac{\theta_{s}}{\left[\ln \left[e + (9.8h/a)^{b} \right] \right]^{c}} \right\}$$
(20)

$$C(h) = \left[1 - \frac{\ln(1 + 9.8h/h_r)}{\ln(1 + 10^6/h_r)}\right]$$
(21)

where *a* is a parameter dependent on air entry value in kPa, *b* is a parameter dependent on the slope of SWCC curve after air entry value is exceeded, *C* is a parameter dependent on the suction at the residual water content, and h_r is a parameter dependent on the suction at the residual water content.

An empirical approach suggested by Zapata et al. [69] was adopted for the calculation of the parameters in the SWCC equation (Eqs. 20, 21). In this method, for a soil with plasticity index (PI) larger than 0, a parameter WPI is introduced, which is the product of PI and the ratio of soil passing ASTM No. 200 sieve (0.075 mm). The parameters were then estimated as:

$$a = 0.00364 (WPI)^{3.35} + 4 (WPI) + 11$$
(22)

$$\frac{b}{c} = -2.313 (\text{WPI})^{0.14} + 5$$
 (23)

$$c = 0.514 (WPI)^{0.465} + 0.5$$
⁽²⁴⁾

$$\frac{h_r}{a} = 32.44 e^{0.0186 \text{WPI}} \tag{25}$$

$$\theta_s = 0.0143 (\text{WPI})^{0.75} + 0.36 \tag{26}$$

The hydraulic conductivity was obtained through the relative permeability function integrated from the SWCC. The effect of temperature-dependent fluid viscosity was neglected for simplification.

$$k_r(h) = \frac{\int_{\ln(h)}^{b} \frac{\theta(e^y) - \theta(h)}{e^y} \theta'(e^y) dy}{\int_{\ln(h_{aev})}^{b} \frac{\theta(e^y) - \theta_s}{e^y} \theta'(e^y) dy}$$
(27)

where b is equal to ln(1000000), y is a dummy variable of integration representing the logarithm of suction, and h_{aev} is the air entry value of matric potential head.

The WPI value for the field subgrade soils was obtained as 21.12 from experimental data on the dense-graded aggregate base and subgrade soil. The subgrade soil was classified as A6 soil by AASHTO specification. A computer code was developed to obtain the SWCCs and the relative permeabilities. The results are shown in Figs. 12 and 13.



Fig. 6 Distribution of the total volumetric water content at different times



Fig. 7 The distribution of volumetric ice content at different times

The parameters for model simulation on the effects of thermal conditions on pavement structure are listed in Table 2.

7.2 Boundary and initial conditions

Neumann boundary conditions, or heat and fluid flux boundaries, were used for the thermal and hydraulic fields, respectively. A Dirichlet boundary condition was assigned for the mechanical field to ensure the boundaries are either free or fixed in a specific direction. Convective heat transfer was assigned along the boundary exposed to the atmosphere (Eq. 17). Based on the duration of the sunshine and surface wind speed data, a constant coefficient, h_c , for convective heat transfer was assumed. The h_c values for pavement and soil surface were assumed to be 25 and 35, respectively, based on typical wind speed data [3]. The influence of short wave and black body radiation was neglected in this study.

The surface water retention can significantly influence the infiltration of water into the pavement base. A conceptual model was formulated for the near-surface water dynamics as following (Eq. 28, [16])

$$\Delta S = P - R - E - T - D \tag{28}$$



Fig. 8 The vertical distribution of matric potential head (absolute value) at different times



Fig. 9 Total vertical deformation versus time

where ΔS is the change in soil water storage, *P* is the precipitation, *R* is the amount of water running off, *E* is the evaporation, *T* is the transpiration of plants, and *D* is the



Fig. 10 The distribution of internal stress under freezing effects

drainage. In this case study, T was neglected and E was assumed to be 2.25×10^{-8} m/s (Delaware County Water Resources).

For the upper boundary of the subgrade, 6% of the precipitation is entered as the influx that can affect the



Fig. 11 Meshed computational domain and boundary



Fig. 12 Soil water characteristic curves of base and subgrade



Fig. 13 Hydraulic conductivity versus suction in base and subgrade

moisture variation of subgrade soil according to local statistics (Delaware County Water Resources). Other than evaporation, water influx into base was controlled by both the cracks and openings of the pavement and the amount of the precipitation. For all the upper boundaries, infiltration was maintained to cease as the matric potential is equal to zero when full saturation is reached. The depth of water table increased from 9.8 feet to 10 feet, an equivalent downward flux of 3.5×10^{-8} m/s as drainage was assigned on the bottom of the computational domain.

The initial temperature and hydraulic field were determined by interpolating field-monitoring data. They were then assigned to the model. The data of air temperature variations and precipitation were applied to the surface boundaries during the model simulation.

8 Results

Figure 14 illustrates the comparison between measured and simulated temperature variation with time at gauge locations S1, S2, and S5. These temperature gauges were buried 1 inch, 4 inches, and 13 inches under the pavement structure, respectively. As can be seen, the trend of temperature variations predicted by the simulation model matches the trend of measured temperature variation at different depths. In fact, temperature fluctuation close to the surface of pavement structure is most difficult to predict, because thermal conductivity was higher for pavement and the effect of the phase change of water on the energy field is more significant there. It is encouraging that our model simulation reasonably captures the trend of thermal field variations close to the surface of pavement structure. Using the measured temperature as the 'true' value, the mean absolute deviation by the model simulation is around 1.1°C and the root mean square of error is around 1.5°C. Potential sources of error include overlooking the effects of solar radiation and wind and approximation of the initial temperature and water distributions.

In Fig. 15, the simulated results of temperature distribution versus depth at 0, 5, and 9 days were plotted. The measured temperature distributions with 18 gauges were also plotted. Simulated results agree very well with the field measured data. The difference of predicted temperature is typically within $\pm 1^{\circ}$ C of measured temperature at most locations. The mean absolute deviation of model simulation results is around 0.3°C, and the root mean square of error is around 0.4°C.

Figure 16 shows the comparison of simulated and measured moisture content distribution at different times. The predicted moisture content distribution matches the field measured trend. It is noticed that the level of errors is slightly larger for the predicted moisture content in the base layer. This is possibly due to the large variation of the hydraulic conductivity at the interface between base and subgrade materials. With exception of the pavement–subgrade interface, the model simulation achieved a mean absolute deviation of around 0.009 m³/m³ and root mean square of error of 0.016 m³/m³. This accuracy is better compared with commonly used uncoupled models

Aubic 2 Fullentere for model simulation of parement strateure	Table 2	Parameters	for 1	model	simulation	of	pavement structure
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Constant	Value	Units	Description
θ_{s1}	0.05	1	Saturated water content of base
θ_{s2}	0.535	1	Saturated water content of subgrade
K_{s1}	8.467×10^{-4}	m/s	Saturated hydraulic conductivity of base
K_{s2}	8.467×10^{-10}	m/s	Saturated hydraulic conductivity of subgrade
n_1	0.3	1	Porosity of base
n_1	0.4	1	Porosity of subgrade
λ_p	1.3	W/m K	Thermal conductivity of asphalt pavement
C _{pp}	2×10^{-6}	J/(m ³ K)	Volumetric heat capacity of asphalt pavement

See Table 1 for other parameters



Fig. 14 Simulated and measure temperature varies with time



Fig. 15 Simulated and measure temperature distributions

such as the Enhanced Integrated Climate Model (EICM, [65]. The model can be used to study the performance of pavement under different climate conditions, such as the



Fig. 16 Simulated and measured moisture content distributions

seasonal variations of resilient moduli, which are important for the durability of pavement [65].

9 Conclusions

A theoretical framework for multiphysics simulations of freezing porous materials is presented in this paper. The thermal, hydraulic, and mechanical fields were coupled together via partial differential equations. The effects of pores on individual physical processes were described by the SWCC and the Clapeyron equation. The highly nonlinear system was solved numerically in a multiphysical simulation platform. The following observations can be made from the simulation results. (1) The thermal-hydro-mechanical fields are strongly coupled in porous materials. Heat transfer induces change in the hydraulic and a stress field, the process is especially important when phase change of pore solutions is involved. (2) Matric potential in unsaturated porous media can cause the volume change pattern that is different solely due to ice formation. (3) Multiphysical simulation described reasonably well the temperature and moisture variations observed under an in-service pavement.

Acknowledgments The authors gratefully acknowledge the help and support from the Ohio Department of Transportation and the Cleveland Water Division during the course of this study. The financial support of this study is partially from NSF project CMMI 0856407.

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